

## **AMENDMENTS TO THE CLAIMS:**

This listing of claims will replace all prior versions and listings of claims in the application:

1. (Currently Amended) An electronic apparatus comprising:  
a disk device having a head;  
a sensor which detects a fall; ~~[[and]]~~  
a control unit configured to control the disk device to move the head to an unload area ~~using a signal which is independent from commands that are processed by the disk device in an order in which they are accepted, when the sensor detects the fall; and~~  
a shock-absorbing unit configured to absorb a shock to the disk device before the head reaches the unload area under the control of the control unit.

2. (Original) The apparatus according to claim 1, wherein the device is a magnetic device, and the head is a magnetic head.

3. (Currently Amended) The apparatus according to claim ~~[[1]]~~ 20, wherein the signal is a reset signal of an interface standard with which the disk device complies.

4. (Currently Amended) The apparatus according to claim ~~[[1]]~~ 20, further comprising:  
an independent signal line configured to exchange the signal, and

wherein the control unit transmits the signal to the disk device via the independent signal line.

5. (Currently Amended) The apparatus according to claim 1, ~~further comprising~~ a wherein the shock-absorbing unit ~~which~~ absorbs a shock that acts upon falling from a height h, when a time required to move the head to the unload area under the control of the control unit is given by a falling time t, satisfies an active-time shockproof specification of the disk device.

6. (Original) The apparatus according to claim 5, wherein a relationship between the falling time t and the height h is defined by:

$$t = (2h/G)^{1/2} \text{ (G: gravitational acceleration)}$$

7. (Original) The apparatus according to claim 1, wherein the sensor is an agravity sensor using a mechanical switch which is opened in an agravity state.

8-19. (Canceled)

20. (New) The apparatus according to claim 1, wherein the control unit controls the disk device using a signal which is independent from commands that are processed by the disk device in an order in which they are accepted.